

Variational Discriminator Bottleneck: Improving Imitation Learning, Inverse RL, and GANs by Constraining Information Flow

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Motivation

The issues of GAN:

- Discriminator is prone to overpowering the generator, which will provide the generator with uninformative gradients for improvement
- Hard to train (unstable or poor performance)

Motivation

How to balance the generator and discriminator?

- To regularize the internal representation by using the information bottleneck
- Modulate the accuracy of discriminator and maintain useful and informative gradient

Preliminaries

Deep Variational information bottleneck

- Given a dataset $\{x,y\}$ with features x and labels y , the standard maximum likelihood estimate $q(y|x)$ can be determined

$$\min_q \mathbb{E}_{\mathbf{x}, \mathbf{y} \sim p(\mathbf{x}, \mathbf{y})} [-\log q(\mathbf{y} | \mathbf{x})]$$

- Prone to overfitting

Preliminaries

- The bottleneck can be incorporated by first introducing an encoder that maps the features \mathbf{x} to a latent distribution over Z . $E(\mathbf{z}|\mathbf{x})$ here is the distribution
- And then enforcing an upper bound I_c on the mutual information between the encoding and the original features $I(X,Z)$. Then the objective:

$$J(q, E) = \min_{q, E} \mathbb{E}_{\mathbf{x}, \mathbf{y} \sim p(\mathbf{x}, \mathbf{y})} \left[\mathbb{E}_{\mathbf{z} \sim E(\mathbf{z}|\mathbf{x})} [-\log q(\mathbf{y}|\mathbf{z})] \right]$$
$$\text{s.t.} \quad I(X, Z) \leq I_c.$$

Preliminaries

- Note that the model $q(y|z)$ now maps samples from the latent distribution z to the label y . The mutual information is defined according to

$$I(X, Z) = \int p(\mathbf{x}, \mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z})}{p(\mathbf{x})p(\mathbf{z})} d\mathbf{x} d\mathbf{z} = \int p(\mathbf{x}) E(\mathbf{z}|\mathbf{x}) \log \frac{E(\mathbf{z}|\mathbf{x})}{p(\mathbf{z})} d\mathbf{x} d\mathbf{z}$$

- A variational lower bound can be obtained by using an approximation $r(z)$ of the marginal $p(z)$

$$I(X, Z) \leq \int p(\mathbf{x}) E(\mathbf{z}|\mathbf{x}) \log \frac{E(\mathbf{z}|\mathbf{x})}{r(\mathbf{z})} d\mathbf{x} d\mathbf{z} = \mathbb{E}_{\mathbf{x} \sim p(\mathbf{x})} [\text{KL} [E(\mathbf{z}|\mathbf{x}) || r(\mathbf{z})]] .$$

Preliminaries

- A variational lower bound = An upper bound on $I(X|Z)$
= An upper bound on the regularized objective:

$$\tilde{J}(q, E) = \min_{q, E} \mathbb{E}_{\mathbf{x}, \mathbf{y} \sim p(\mathbf{x}, \mathbf{y})} \left[\mathbb{E}_{\mathbf{z} \sim E(\mathbf{z}|\mathbf{x})} [-\log q(\mathbf{y}|\mathbf{z})] \right]$$
$$\text{s.t.} \quad \mathbb{E}_{\mathbf{x} \sim p(\mathbf{x})} [\text{KL} [E(\mathbf{z}|\mathbf{x}) || r(\mathbf{z})]] \leq I_c.$$

- This can be solved by introducing the Lagrange multiplier

$$\min_{q, E} \mathbb{E}_{\mathbf{x}, \mathbf{y} \sim p(\mathbf{x}, \mathbf{y})} \left[\mathbb{E}_{\mathbf{z} \sim E(\mathbf{z}|\mathbf{x})} [-\log q(\mathbf{y}|\mathbf{z})] \right] + \beta \left(\mathbb{E}_{\mathbf{x} \sim p(\mathbf{x})} [\text{KL} [E(\mathbf{z}|\mathbf{x}) || r(\mathbf{z})]] - I_c \right).$$

VDB

- Standard GAN:

$$\max_G \min_D \mathbb{E}_{\mathbf{x} \sim p^*(\mathbf{x})} [-\log(D(\mathbf{x}))] + \mathbb{E}_{\mathbf{x} \sim G(\mathbf{x})} [-\log(1 - D(\mathbf{x}))]$$

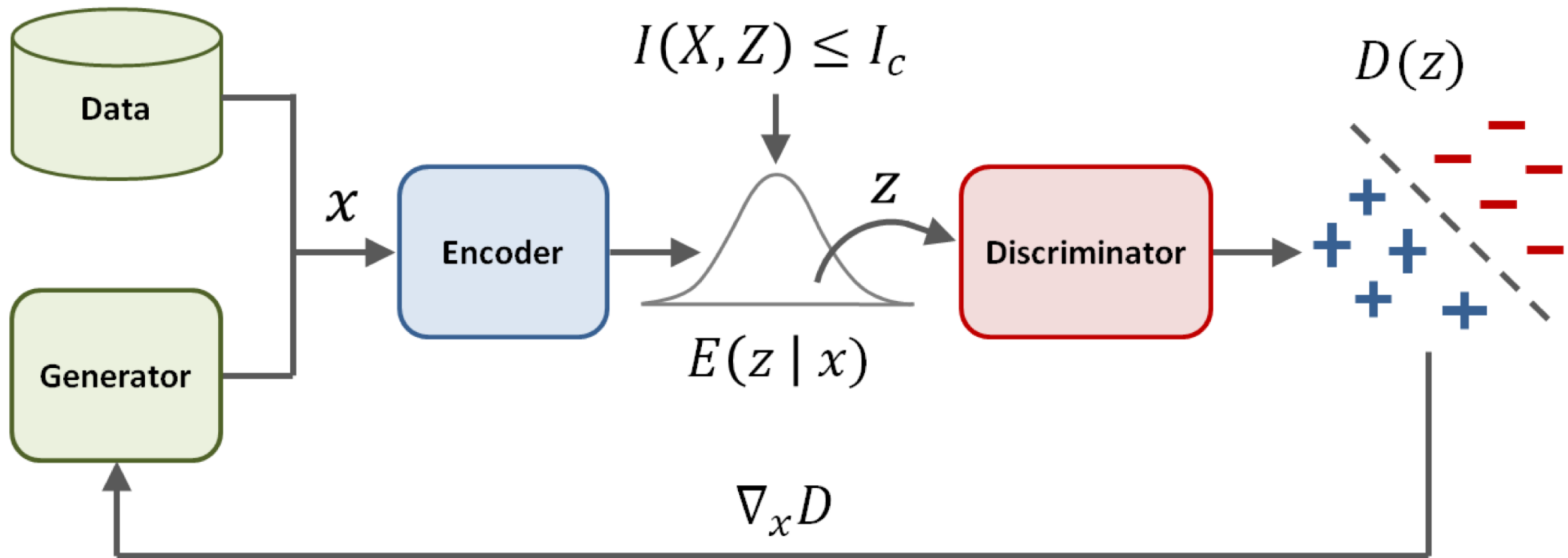
- Introduce an encoder E into discriminator that maps a sample x into a stochastic encoding z , and then apply the information bottleneck I_c on the mutual information $I(X,Z)$

$$J(D, E) = \min_{D, E} \mathbb{E}_{x \sim p^*(\mathbf{x})} [\mathbb{E}_{z \sim E(\mathbf{z}|\mathbf{x})} [-\log(D(\mathbf{z}))]] + \mathbb{E}_{\mathbf{x} \sim G(\mathbf{x})} [\mathbb{E}_{z \sim E(\mathbf{z}|\mathbf{x})} [-\log(1 - D(\mathbf{z}))]]$$

s.t. $\mathbb{E}_{\mathbf{x} \sim \tilde{p}(\mathbf{x})} [\text{KL}[E(\mathbf{z}|\mathbf{x}) || r(\mathbf{z})]] \leq I_c,$

$$\tilde{p} = \frac{1}{2}p^* + \frac{1}{2}G$$

VDB



VDB

- Objective (Discriminator) with dual gradient descent:

$$J(D, E) = \min_{D, E} \max_{\beta \geq 0} \mathbb{E}_{\mathbf{x} \sim p^*(\mathbf{x})} [\mathbb{E}_{\mathbf{z} \sim E(\mathbf{z}|\mathbf{x})} [-\log(D(\mathbf{z}))]] + \mathbb{E}_{\mathbf{x} \sim G(\mathbf{x})} [\mathbb{E}_{\mathbf{z} \sim E(\mathbf{z}|\mathbf{x})} [-\log(1 - D(\mathbf{z}))]] \\ + \beta (\mathbb{E}_{\mathbf{x} \sim \tilde{p}(\mathbf{x})} [\text{KL}[E(\mathbf{z}|\mathbf{x})||r(\mathbf{z})]] - I_c).$$

$$D, E \leftarrow \arg \min_{D, E} \mathcal{L}(D, E, \beta)$$

$$\beta \leftarrow \max(0, \beta + \alpha_\beta (\mathbb{E}_{\mathbf{x} \sim \tilde{p}(\mathbf{x})} [\text{KL}[E(\mathbf{z}|\mathbf{x})||r(\mathbf{z})]] - I_c))$$

VDB

- Objective (Generator) with approximation, directly use the mean:

$$\max_G \mathbb{E}_{\mathbf{x} \sim G(\mathbf{x})} [-\log (1 - D(\mu_E(\mathbf{x})))]$$

Experiments

- video

Conclusion

- Prevent overfitting in GAN/VAE is crucial
- The VDB framework provides a way to achieve better representation
- How to select the I_c ?
- Any potential way to combine pre-trained representation with VDB?